



1. Have controller in MECHANICAL ZERO screen and document readings  
|MENU| |CALIBRATE| |ZERO|MECHANICAL ZERO|
2. The display “yellow” bar should move then return to approximately the same value as reading #1 with each tilt
3. If after it settles for a few seconds you see drastic difference in readings #2 or #3 from #1, for example >30% change in value, report values back to technical support as this may be a sign of a damaged sensor

